Homotopy and the complexity of homomorphism problems Jakub Opršal et al.



joint work with Sebastian Meyer (TU Dresden)



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of values to *variables* that satisfies a given set of *constraints*.

Bulatov–Zhuk Theorem [Bulatov, 2017; Zhuk, 2017] For every finite structure *A*, CSP(*A*) is NP-complete or in P.

CSP(A) is the problem of deciding whether a given structure *B* (in the same language) maps homomorphically to *A*.

Fact. There is no FO-sentence ϕ in the language of graphs such that

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Why is homotopy theory so effective in computational complexity of CSPs?

Part I. What problems am I talking about?

Graph colouring



Graph colouring



Given two graphs $G = (V_G, E_G)$ and $H = (V_H, E_H)$, a graph homomorphism $G \to H$ is a mapping $h: V_G \to V_H$ that preserves edges,

$$uv \in E_G \Rightarrow h(u)h(v) \in E_H.$$

Example. A colouring of a graph *G* with *k* colours is just a homomorphism $c: G \to K_k$.

The *H*-colouring problem

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H-colouring

Fix a graph *H* (called *template*). Given a graph *G*, decide whether there is a homomorphism $G \rightarrow H$.

- ► K₂-colouring is easy (it is solvable in logspace [Reingold, 2005]);
- K_k -colouring is NP-complete for all k > 2.
- ► What about other graphs *H*?

Theorem [Hell & Nešetřil, 1990].

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Outline of a new proof

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- 1. Identify which problems are NP-hard using the *algebraic approach to the constraint satisfaction problem*.
- 2. If *H*-colouring is not NP-hard, show that its *solution spaces* are component-wise contractible.
- 3. Use Brower's fixed-point theorem to show that *H* has a loop if *H* is not bipartite.

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Part II. What the ... is the solution space of *H*-colouring?

A multihomomorphism is a function $f: V(G) \rightarrow 2^{V(H)} \setminus \{\emptyset\}$ such that, for all edges $uv \in E(G)$, we have that

 $f(u) \times f(v) \subseteq E(H).$

Multihomomorphisms are naturally ordered

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Solution spaces

Given graphs G and H, we define the space

Hom(G, H) = |N mhom(G, H)|

- ► The vertices are multihomomorphisms,
- f and g are connected by an arc if $f \leq g$,
- $\{f, g, h\}$ form a triangle if $f \le g \le h$,
- etc.

We view this as the solution space of instance G of H-colouring.

Example. Hom $(K_2, K_3) \simeq S^1$. Example. In mhom (K_2, K_4) we have: $0-1 \le 02-1 \le 02-13$ and $0-1 \le 0-12 \le 0-123$ which creates 2-dimensional faces.

Two colourings f and g are connected if g can be obtained from f by **changing one value at a time** while remaining a valid colouring.

4-colourings of K_2









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Part III. A proof

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Theorem (CSP Dichotomy).

- A CSP with a finite template A either
 - admits a Taylor homomorphism t: Aⁿ → A, and is in P [Bulatov, 2017; Zhuk, 2017]; or
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Theorem [Bulatov, 2005; Siggers, 2005].

A loopless core graph *H* has a Taylor homomorphism if and only if it is bipartite.

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Lemma [Taylor, 1977]. If a topological space X admits a continuous idempotent Taylor operation t, then $\pi_1(X)$ is Abelian. $t: A^n \to A$ is idempotent if $t(x, ..., x) \approx x$.

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$\textbf{Taylor} \rightarrow \textbf{contractibility}$

A topological space X is called contractible if it is homotopy equivalent to a point {*}. For us, this is equivalent to $\pi_n(X) = 0$ for all $n \ge 0$.

Theorem [Larose, Zádori, 2005].

Every connected finite poset that admits a monotone Taylor operation is contractible.

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Nevertheless, there is a lax-Taylor monotone operation t: mhom $(G, H)^n \rightarrow \text{mhom}(G, H)$ that satisfies:

$$\begin{array}{cccc} t(x & * & \dots & *) \ge s_1(x, y) \le t(y & * & \dots & *) \\ t(* & x & \dots & *) \ge s_2(x, y) \le t(* & y & \dots & *) \\ & & & \vdots \\ t(* & * & \dots & x) \ge s_n(x, y) \le t(* & * & \dots & y) \end{array}$$

for all $x, y \in A$.

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Theorem [Meyer, **0**, 2025].

Every connected finite poset that admits a monotone lax-Taylor operation is contractible, and therefore Hom(G, H) is component-wise contractible for all G if H has a Taylor polymorphism.



Hence, 4-colouring is NP-hard!
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A fixed-point theorem

Theorem (Brower's fixed-point theorem).

Every continuous function $f: D^n \to D^n$ *has a fixed point, i.e., there exists* $x \in D^n$ *such that* f(x) = x.

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Every continuous function $f: D^n \to D^n$ has a fixed point, i.e., there exists $x \in D^n$ such that f(x) = x.

More generally: If X is a contractible compact CW-complex, then every function $f: X \to X$ has a fixed point.

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The proof

Theorem [Hell, Nešetřil, 1990].

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Proof. Assume that *H* is not-bipartite, and consider the space $X = Hom(K_2, H)$.

Observe that the space admits a fixed-point free \mathbb{Z}_2 -action $\phi: X \to X$ that for each multihomomorphism *m* flips the values of *m*(0) and *m*(1).

If *H* is not-bipartite then ϕ fixes a connected component of *X*. Indeed, if uv is an edge of an odd cycle of *H* then uv is connected to $vu = \phi(uv)$.

If *H* admitted a Taylor homomorphism, mhom(K_2 , *H*) would admit a lax-Taylor operation, and all its connected component would be contractible.

Hence, ϕ which acts on the component of uv has a fixed point, the contradiction.

How it started...

Conjecture [Brakensiek, Guruswami, 2018].

Colouring graphs that are promised to map homomorphically to $C_{(2k+1)}$ with c colours is NP-complete for all c > 2 and k > 0.

- [1] Krokhin, **O** (2019). The complexity of 3-colouring *H*-colourable graphs. *FOCS 2019*.
- [2] Wrochna, Živný (2020). Improved hardness for *H*-colourings of *G*-colourable graphs. SODA 2020.
- [3] Avvakumov, Filakovský, O, Tasinato, & Wagner (2025). Hardness of 4-colouring G-colourable graphs. STOC 2025.

Theorem [Avvakumov et al., 2025].

Colouring graphs that are promised to map homomorphically to $C_{(2k+1)}$ with 4 colours is NP-complete.

[4] Filakovský, Nakajima, O, Tasinato, & Wagner (2024). Hardness of Linearly Ordered 4-Colouring of 3-Colourable 3-Uniform Hypergraphs *STACS 2024*.

- [1] Schnider, Weber (2024). A topological version of Schaefer's dichotomy theorem. *SoCG 2024*.
- [2] Meyer (2024). A dichotomy for finite abstract simplicial complexes. *arXiv:2408.08199*.
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Theorem [Meyer, 2024; Meyer, **0**, 2025].

A constraint satisfaction problem is NP-complete, unless each connected component of the solution space is contractible (i.e., topologically trivial).

Corollary [Hell & Nešetřil, 1990].

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 [4] Briceño, Bulatov, Dalmau, Larose (2021). Dismantlability, connectedness, and mixing in relational structures. *JCT B* 147: 37–70.

Theorem [Briceño et al., 2017].

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